Keyword Spotting

Small Footprint Model under Noisy Far-field Environment

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Abstract

Building a small memory footprint keyword spotting model is important as it typically runs on mobile devices with low computational resources. In real life, noisy environment with some reverberations is degrading the performance of a keyword spotting (KWS) model. We proposed a novel feature interactive convolution (ConvMixer) model with small parameters for single-channel and multichannel utterance. Moreover, we proposed a centroid-based awareness component to improve multi-channel system by providing some the additional spatial geometry information in the latent. Our proposed model achieved the best performance feature projection space.

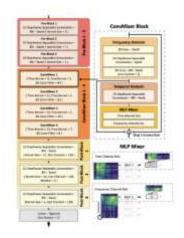
Introduction

Small models face a tough challenge in KWS task in noisy environments.

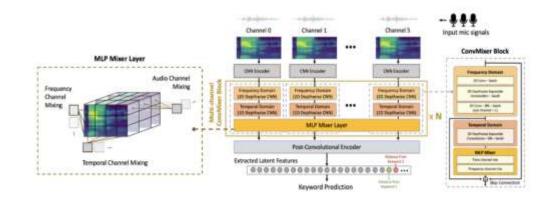
- ConvMixer The model can outperform some novel small neural network models like ResNet and attain robustness in noisy farmulti-channel field single-channel and signals.
- the centroid vector for better estimate performance.

Approach

Single-channel model



Multi-channel model



among SOTA small footprint models.

Single-channel model



Multi-channel model with centroid-based awareness



Conclusion

The accuracy of single-channel ConvMixer in **Centroid-based Awareness** – Use the Google Speech Command is 98.20% and in an distance between input and keywords to average of four different SNRs in far-field is 76.94%. For multi-channel ConvMixer, it reaches the best accuracy of 94.3% and the lowest score of 0.152 with the use of centroidbased awareness in MISP dataset.